

SmartStix Analogue I/O Modules High Speed Remote I/O for the i3 Family **GCL-AT0A / GCL-AT1A**



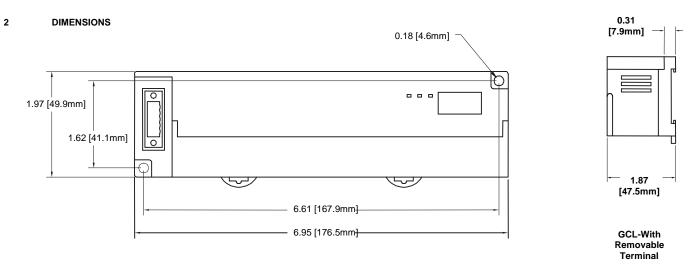
4 Input Channels, 2 Output Channels / 8 Input Channels, 4 Sourcing Output Channels ±5V / ±10V / 4-20mA / ±20mA

SPECIFICATIONS

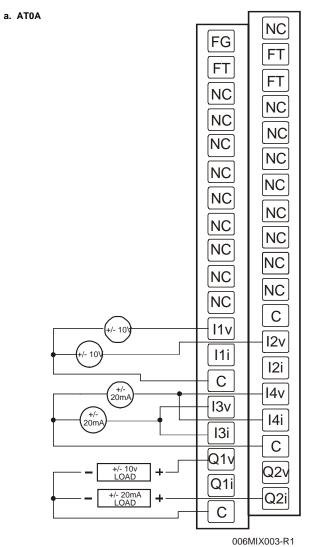
			ΔΝΔ	LOGUE IN				
	±5\	/, ±10V DC					1000V DC	
Input Ranges		Á, ±20mA DO	2	Isolation			IEC61010-1 300V RMS	
Resolution		14 bits		Isolation Me	ethod		Magnetic	
Input Impedance		1 Megohm		Maximum C	ontinuous Overload	d	±10V: 150VAC	
		: 150 Ohms					±20mA: ±30mA, Clamped at ±6V	
Filter Modes	Running Av	verage or Ada		OGUE OUT	ble Filter Time Con	stants	0.01 to 1.28 Seconds	
			ANAL				1000V DC	
Output Ranges		, ±10V DC	_	Isolation			IEC61010-1 300V RMS	
3.1	4-20m	A, ±20mA DC	3	Isolation Me	ethod		Magnetic	
Resolution		14 bits		Output Clan	np		±12V, 600Wpk	
Load Resistance		: 600 Min		Output Char	racteristic		Sourcing	
	m/	A: 500 Max		-				
		0.014/	GI	ENERAL				
Required Power (Steady State)	/45	3.6W 50ma @ 24VE) ()	Opera	ting Temperature		0° to 55° C	
	,		· ·	Operat	ting and Storage Hu	ımidity	5 to 95% Non-condensing	
Required Power (Inrush)	8A @	@ 24VDC for	1ms		le for use	annuncy	Up to 2,000m	
Storage Temperature		-25° to 70° C	;		ion degree		2 or lower	
Atmosphere	Free from corros	sive gases an	d excessiv	e dust Coolin	ig method		Self-cooling	
			V	ibration				
			Occasio	onal Vibration				
Frequency	Acceleration	Ampl	litude			Sweep Co	ount	
	Acceleration					oweep C	Juni	
10 ≤ f < 57 Hz	-	0.075	5 mm		10 times in	ection for X,Y,Z		
57 ≤ f ≤ 150 Hz	9.8 m/s ² {1G}	-	-			reach direction of $\lambda, 1, 2$		
			Continu	ous Vibration				
Frequency	Ampl	litude		:	Sweep Co	ount		
· · · · · · · · · · · · · · · · · · ·	Acceleration		·					
10 ≤ f < 57 Hz	-	0.035 mm 10 times in 6					ection for X,Y,Z	
57≤ f ≤ 150 Hz	4.9 m/s ² {0.5G}	-						
				Shocks				
Maximum shock acceleration					147 m/s ² {150	3}		
Duration Time					11 ms.	-1		
							- "	
Pulse Wave					pulse (3 times in each	cn of X, Y,	Z directions)	
		T	Nois	e Immunity				
Square wave impulse noise		AC: ± 1,500VDC DC: ± 900VDC						
Electrostatic Discharge		Voltage: 4kV (contact discharge)						
Radiated electromagnetic field					27 – 500MHz, 10		<u> </u>	
					2. 00012, 10	, , , , , ,	Digital I/Os	
Fast Transient		Severity le	All pow		Digital I/Os	;	(Ue < 24 V)	
Burst Noise		Severity is	7 4 61	modules	(Ue ≥24V)		Analogue I/Os	
				0111	4114		Communication I/Os	
		Voltag	е	2 kV AT0A	1 kV		0.25 kV AT1A	
ANALOGUE IN				ATUA			ATTA	
Number of input points				4			8	
Conversion Time			5ms for all Channels				10ms for all Channels	
Accuracy, 25℃			0.3%				0.1%	
Register Value for Nominal Full Sc	ale			32000			±32000	
ANALOGUE OUT							4	
	Number of output points				2			
Number of output points				0.3%			0.407	
Number of output points Accuracy, 25℃							0.1%	
Number of output points Accuracy, 25℃ Register Value for Nominal Full So	ale			0.3% 32000		3 chan	±32000	
Number of output points Accuracy, 25℃	ale					3 chanr		

Refer to SmartStix Remote I/O Tutorial: http://www.imopc.com/download/912/i3-tutorial-remote-i-o.html





WIRING

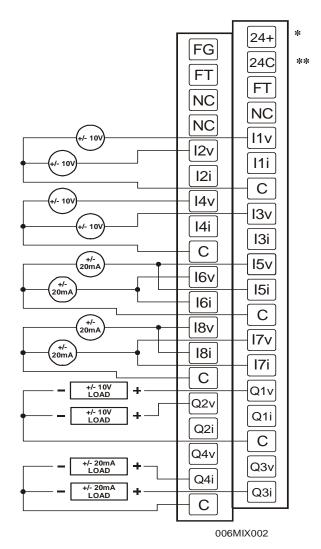


Λ-	ГОА	A	T0A
		1	NC
2	FG	3	FT
4	FT	5	FT
6	NC	7	NC
8	NC	9	NC NC
10	NC		
12	NC	11	NC
14	NC	13	NC
16	NC	15	NC
18	NC NC	17	NC
		19	NC
20	NC	21	NC
22	NC	23	C
24	l1v	25	I2v
26	l1i	27	12i
28	С		
30	l3v	29	I4v
32	l3i	31	l4i
34	Q1v	33	С
		35	Q2v
36	Q1i	37	Q2i
38	С		

FT: Factory Test, Do Not Connect FG: Frame Ground

C terminals are connected together internally but isolated from bus and power circuits.

b. AT1A



Technology Group

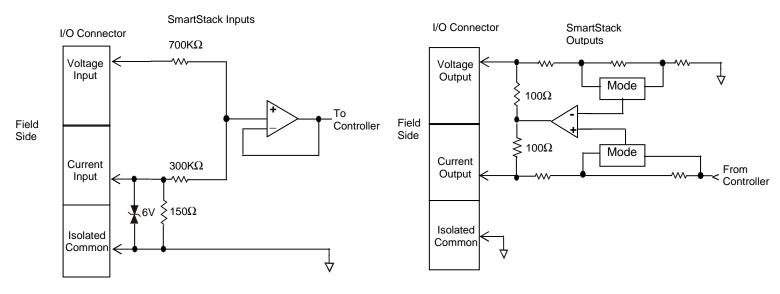
Δ-	Г1А	A	T1A
2	FG	1	24+ *
		3	24C **
4	FT	5	FT
6	NC	7	NC
8	NC	9	I1v
10	l2v	11	I1i
12	l2i		
14	I4v	13	С
16	l4i	15	l3v
18	С	17	l3i
20	l6v	19	l5v
22	16i	21	l5i
		23	С
24	I8v	25	17v
26	l8i	27	17i
28	С	29	Q1v
30	Q2v	31	Q1i
32	Q2i		
34	Q4v	33	C
36	Q4i	35	Q3v
38	C	37	Q3i

FT: Factory Test, Do Not Connect FG: Frame Ground

C terminals are connected together internally but isolated from bus and power circuits.

* and ** For iCAN and DeviceNet versions, module power is usually derived from the CAN connector. In that case, +24VDC and 24C are not connected.

4 INTERNAL WIRING



Specifications/Installation

5 CHANNEL MODE, PROGRAMMABLE FILTER, AND OUTPUT DEFAULT CONFIGURATION

The network supplies configuration information to the unit in the Consumed Directed Digital Data Words sent to the unit. In the first word, the low 12 bits, 1 through 12, are channel mode bits. A low mode bit selects ±10V and a high mode bit selects ±20mA. The next three bits, 13 through 15, are input digital filter time constant codes and the high bit, 16, is an adaptive filter enable bit. In the second word, the low 12 bits are channel scale bits. A low scale bit selects ±10V or ±20mA for the corresponding channel. A high scale bit selects ±5V or 4-20mA. The upper four bits are unused.

Bit	AT0A Channel	AT1A Channel		
1	Al1	Al1		
2	Al2	Al2		
3	Al3	Al3		
4	Al4	Al4		
5	Not used	AI5		
6	Not used	Al6		
7	Not used	AI7		
8	Not used Al8			
9	AQ1	AQ1		
10	AQ2	AQ2		
11	Not used	AQ3		
12	Not used	AQ4		

Each analogue input on the unit has a single pole 345Hz (461uS) cutoff high frequency noise filter. In addition a second digital filter may be specified in the first configuration word with the following time constants.

	Bit		Time Constant
15	14	13	
0	0	0	10 milliseconds (Nominal hardware scan rate)
0	0	1	15 milliseconds
0	1	0	35 milliseconds
0	1	1	75 milliseconds
1	0	0	155 milliseconds
1	0	1	315 milliseconds
1	1	0	635 milliseconds
1	1	1	1.275 seconds

This digital filter is useful for applications with significant amounts of random noise. The slower time constants, while yielding better noise suppression, take a longer time to settle after step changes and are also sensitive to impulse noise which is treated like Gaussian noise and averaged.

Bit 16 of the first configuration word may be set to specify an adaptive filter algorithm that:

- 1. Responds much more quickly to large step changes at slower time constants with full filtering of low level noise.
- 2. Suppresses impulse noise at the expense of slightly slower response at the shortest time constant settings. (Approximately 10 additional milliseconds)

Note that actual system response time is network dependent.

Bits 9 through 12 of the 5th configuration word control the behavior of the analogue outputs when network communication is lost. The bit to channel correspondence is the same as for the mode and scale bits. If the corresponding bit is set, the outputs hold the last state. If the corresponding bit is cleared, the outputs are set to the respective value supplied to the unit in the second four words of the Consumed Directed Analogue Data sent by the i3. The other bits of the 5th configuration word are unused.

Refer the Remote I/O Tutorial. http://www.imopc.com/download/912/i3-tutorial-remote-i-o.html

6 INPUT AND OUTPUT CONVERSION FACTORS

The following table describes how real-world values are scaled in the controller. For a given physical voltage or current, the register data value may be calculated by using the conversion factor from the table. The following formula is used: **Data = Voltage or Current / Conversion Factor**.

Example: The user selects a voltage range of ±10V:

- The physical voltage is 6 Volts.
- Using the table, the conversion factor for the voltage range of ±10V is .0003125.
- 3. To determine the data value, the formula is used: Data = V / Conversion Factor

19200 = 6 VDC / 0.0003125

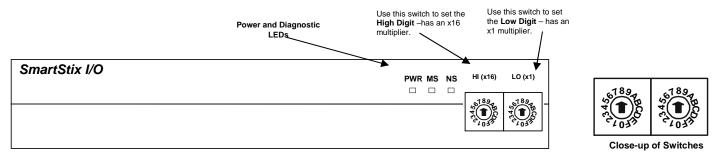
Calcata d Danina		tween Physical Values and Register Values	
Selected Range	Volts / mA	Register Data	Conversion Factor
	> +5.11	32767	
	+5.00	32000	
±5.00 V	0.00	0	0.00015625
	-5.00	-32000	
	< -5.11	-32768	
	> +10.23	32767	
±10.00 V	+10.00	32000	
	0.00	0	0.0003125
	-10.00	-32000	
	< -10.23	-32768	
	< +20.37	32767	
	+20.00	32000	
420 mA	+4.00	0	0.0005
	-12.00	-32000	
	> -12.38	-32768	
	> +20.47	32767	
	+20.00	32000	
±20.00 mA	0	0	0.0006250
Ī	-20.00	-32000	
	< -20.47	-32768	



SETTING ID SWITCHES

iCAN Network IDs are set using the hexadecimal number system from 01 to FD. The decimal equivalent is 1-253. Refer to following Conversion Table, which shows the decimal equivalent of hexadecimal numbers. Set a unique Network ID by inserting a small Phillips screwdriver into the two *identical* switches.

Note: The iCAN Baud Rate for SmartStix I/O is fixed at 125KBaud.



						Decimal	(Dec) to	Hexade	cimal (Hex	Conve	rsion						
Dec	H	Hex Dec Hex Dec Hex Dec Hex Dec Hex Dec						Н	Hex								
	н	LO		н	LO		н	LO		н	LO		н	LO		н	LO
			46	2	Е	92	5	С	138	8	Α	184	В	8	230	Е	6
1	0	1	47	2	F	93	5	D	139	8	В	185	В	9	231	Е	7
2	0	2	48	3	0	94	5	Е	140	8	С	186	В	Α	232	Е	8
3	0	3	49	3	1	95	5	F	141	8	D	187	В	В	233	E	9
4	0	4	50	3	2	96	6	0	142	8	Е	188	В	С	234	Е	Α
5	0	5	51	3	3	97	6	1	143	8	F	189	В	D	235	Е	В
6	0	6	52	3	4	98	6	2	144	9	0	190	В	Е	236	Е	С
7	0	7	53	3	5	99	6	3	145	9	1	191	В	F	237	Е	D
8	0	8	54	3	6	100	6	4	146	9	2	192	С	0	238	Е	Е
9	0	9	55	3	7	101	6	5	147	9	3	193	С	1	239	Е	F
10	0	Α	56	3	8	102	6	6	148	9	4	194	С	2	240	F	0
11	0	В	57	3	9	103	6	7	149	9	5	195	С	3	241	F	1
12	0	С	58	3	Α	104	6	8	150	9	6	196	C	4	242	F	2
13	0	D	59	3	В	105	6	9	151	9	7	197	С	5	243	F	3
14	0	Е	60	3	С	106	6	Α	152	9	8	198	С	6	244	F	4
15	0	F	61	3	D	107	6	В	153	9	9	199	С	7	245	F	5
16	1	0	62	3	Е	108	6	С	154	9	Α	200	С	8	246	F	6
17	1	1	63	3	F	109	6	D	155	9	В	201	С	9	247	F	7
18	1	2	64	4	0	110	6	Е	156	9	С	202	С	Α	248	F	8
19	1	3	65	4	1	111	6	F	157	9	D	203	С	В	249	F	9
20	1	4	66	4	2	112	7	0	158	9	Е	204	С	С	250	F	Α
21	1	5	67	4	3	113	7	1	159	9	F	205	С	D	251	F	В
22	1	6	68	4	4	114	7	2	160	Α	0	206	С	Е	252	F	С
23	1	7	69	4	5	115	7	3	161	Α	1	207	С	F	253	F	D
24	1	8	70	4	6	116	7	4	162	Α	2	208	D	0			
25	1	9	71	4	7	117	7	5	163	Α	3	209	D	1	1		
26	1	Α	72	4	8	118	7	6	164	Α	4	210	D	2	1		
27	1	В	73	4	9	119	7	7	165	Α	5	211	D	3	1		
28	1	С	74	4	Α	120	7	8	166	Α	6	212	D	4	1		
29	1	D	75	4	В	121	7	9	167	Α	7	213	D	5	1		
30	1	E	76	4	С	122	7	Α	168	Α	8	214	D	6			
31	1	F	77	4	D	123	7	В	169	Α	9	215	D	7			
32	2	0	78	4	Е	124	7	С	170	Α	Α	216	D	8			
33	2	1	79	4	F	125	7	D	171	Α	В	217	D	9	J		
34	2	2	80	5	0	126	7	Е	172	Α	С	218	D	Α	J		
35	2	3	81	5	1	127	7	F	173	Α	D	219	D	В	J		
36	2	4	82	5	2	128	8	0	174	Α	Е	220	D	С	J		
37	2	5	83	5	3	129	8	1	175	Α	F	221	D	D			
38	2	6	84	5	4	130	8	2	176	В	0	222	D	Е	J		
39	2	7	85	5	5	131	8	3	177	В	1	223	D	F	J		
40	2	8	86	5	6	132	8	4	178	В	2	224	E	0	J		
41	2	9	87	5	7	133	8	5	179	В	3	225	E	1]		
42	2	Α	88	5	8	134	8	6	180	В	4	226	E	2]		
43	2	В	89	5	9	135	8	7	181	В	5	227	E	3]		
44	2	С	90	5	Α	136	8	8	182	В	6	228	E	4]		
45	2	D	91	5	В	137	8	9	183	В	7	229	E	5	J		

8 LEDS

SmartStix I/O Modules provide diagnostic and status LED indicators.

a. Diagnostic LED Indi	cators		b. Status LED Indicators
Diagnostic LED	State	Meaning	The Power Status LED illuminates Red when power is applied to
	Solid Red	RAM or ROM test failed	the module. There are I/O Status LED indicators for each of the
MS	Blinking Red	I/O test failed, internal hardware fault	Digital I/O points, which illuminate Red when an I/O point is ON.
(Module Status)	Blinking Green	Module is in power-up state *	
	Solid Green	Module is running normally	
	Solid Red	Network Ack or Dup ID test failed **	
NS	Blinking Red	Network ID test failed: ID not in the range of 1253	
(Network Status)	Blinking Green	Life Expectancy timeout, outputs are in default state ***	
	Solid Green	Network is running normally	
expected configuration for Configuration, not having	rom the i3. This may be downloaded the Netw	more than a few seconds the module has not received the be due to no Network I/O configuration created in i3 vork I/O configuration to the master i3, an unpowered at on the module's rotary switches.	
		active on the network. Dup ID test failed means that is already on the network.	
	either the Life Expec	odule has not received a periodic message from the master tancy directed data message or the Comm timeout of the jurator.	

9 NETWORK CABLE

For detailed wiring information, refer to the Remote I/O Tutorial. http://www.imopc.com/download/912/i3-tutorial-remote-i-o.html

		Pin	Description
0	RED	1	V+
0	WHT	2	CAN_H
0	NC	3	No Connection
0	BLU	4	CAN_L
0	BLK	5	V-

Recommended Cable						
Thick: (Max Distance = 500m) Belden 3082A						
Thin: (Max Distance = 100m)	Belden 3084A					

10 INSTALLATION / SAFETY

When found on the product, the following symbols specify:



Warning: Consult user documentation.

WARNING: To avoid the risk of electric shock or burns, always connect the safety (or earth) ground before making any other connections.

WARNING: To reduce the risk of fire, electrical shock, or physical injury it is strongly recommended to fuse the voltage measurement inputs. Be sure to locate fuses as close to the source as possible.

WARNING: Replace fuse with the same type and rating to provide protection against risk of fire and shock hazards.

WARNING: In the event of repeated failure, do <u>not</u> replace the fuse again as a repeated failure indicates a defective condition that will <u>not</u> clear by replacing the fuse.

WARNING: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.



Warning: Electrical Shock Hazard.

For detailed installation and panel box layout requirements and minimum clearances, refer to the hardware manual of the controller you are using. (See the **Additional References** section in this document.).

- All applicable codes and standards need to be followed in the installation of this product.
- For I/O wiring (discrete), use the following wire type or equivalent: Belden 8441 or equivalent.

Adhere to the following safety precautions whenever any type of connection is made to the module.

- Connect the green safety (earth) ground first before making any other connections.
- When connecting to electric circuits or pulse-initiating equipment, open their related breakers.
 Do not make connections to live power lines.
- Make connections to the module first; then connect to the circuit to be monitored.
- Route power wires in a safe manner in accordance with good practice and local codes.
- Wear proper personal protective equipment including safety glasses and insulated gloves when making connections to power circuits.
- Ensure hands, shoes, and floor are dry before making any connection to a power line.
- Make sure the unit is turned OFF before making connection to terminals. Make sure all circuits are de-energized before making connections.
- Before each use, inspect all cables for breaks or cracks in the insulation. Replace immediately if defective.

11 TECHNICAL ASSISTANCE

For assistance and manual updates, contact Technical Support: $\underline{automation@imopc.com}$